## Department of Mechanical, Materials and Manufacturing Engineering



The University of Nottingham

## Computer Engineering and Mechatronics MMME/3085

## Exercise Sheet 1: Hexadecimal code and bit manipulation

- 1. Convert the following binary numbers to hexadecimal:
  - a. 10101100<sub>B</sub>
  - b. 1110101011110101<sub>B</sub>
- 2. Convert the following hexadecimal numbers to binary:
  - а. 10н
  - b. 8D<sub>H</sub>
- 3. Evaluate the following expressions in the C language (note that 0xA1 means  $A1_{H}$ ) expressing your answers in hex and binary. Assume the number is stored in an 8-bit variable so overflows and underflows beyond that capacity will be lost.
  - a. 0xA1 << 2;
  - b. 0xF4 >> 3;
- 4. Evaluate the following expressions in the C language:
  - a. 0xAA | 0xB1;
  - b. 0xBC & 0x3A;
- 5. (You will need to understand 5 and 6 to make sense of Lecture 2!) A control byte on the Atmega2560 is to be set using the following constants which are defined as follows:

WGM52 = 3, CS52 = 2, CS50 = 0. What is the value in TCCR1B after executing this line? (This process is known as "setting" bits).

TCCR1B = (1 << WGM52) | (1 << CS52) | (1 << CS50);

6. DDRB initially contains the value 0xC2. What value does it contain after executing the following line, if DDB1 = 1 and DDB6 = 6? (This process is known as "resetting" or "clearing" bits).

 $DDRB = DDRB \& \sim (1 << DDB1) \& \sim (1 << DDB6);$